WHAT IS CLAIMED IS:

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1. A method for controlling a mobile satellite tracking antenna system, the method comprising the steps of:

receiving satellite signals and sensing whether or not the satellite signals are intercepted; performing a satellite signal automatic tracking mode when the received signals have a restorable level after rotating an antenna 360°, and comparing maximum variation of signal level measured through 360° rotation of the antenna with a room temperature noise signal level range when the received signals do not have a restorable level;

performing a satellite detection mode when the maximum variation of the measured signal level deviates from the room temperature noise signal level range, and stopping a rotation motor of the antenna from driving when the maximum variation of the measured signal level exists in the room temperature noise signal level range; and

driving the rotation motor of the antenna again when a predetermined time passes after the rotation of the antenna has been stopped, measuring signal levels while rotating the antenna 360°, and comparing the maximum variation of the measured signal level with the room temperature noise signal level range.

- 2. The method for controlling a mobile satellite tracking antenna system as claimed in claim 1, wherein the signal level is continuously measured even after the rotation motor of the antenna is stopped.
- 3. A method for controlling a satellite tracking system, the method comprising the steps of:

receiving satellite signals;

comparing a maximum variation of signal level measured through a 360° rotation of an antenna with a room temperature noise signal level range when the received signals do not have a restorable level; and

performing a satellite detection mode when the maximum variation of the measured signal level deviates from the room temperature noise signal level range.

- 4. The method of claim 3, further comprising stopping rotation of a motor of the antenna from driving when the maximum variation of the measured signal level exists in the room temperature noise signal level range.
- 5. The method of claim 3, further comprising, after said receiving, sensing whether or not the satellite signals are intercepted.

- 6. The method of claim 3, further comprising, after said receiving, performing a satellite signal automatic tracking mode when the received signals have a restorable level after rotating an antenna 360°.
- 7. The method of claim 3, further comprising rotating a motor of the antenna when a predetermined time passes after rotation of the antenna has been stopped.
 - 8. The method of claim 7, further comprising measuring signal levels while rotating the antenna 360°.
 - 9. The method of claim 8, further comprising comparing the maximum variation of the measured signal level with the room temperature noise signal level range.
- 10 The method of claim 3, wherein the signal level is continuously measured even after the rotation motor of the antenna is stopped.